

Segregated Airspace

Anastasio Sánchez Center for Advanced Aerospace Technologies (CATEC)

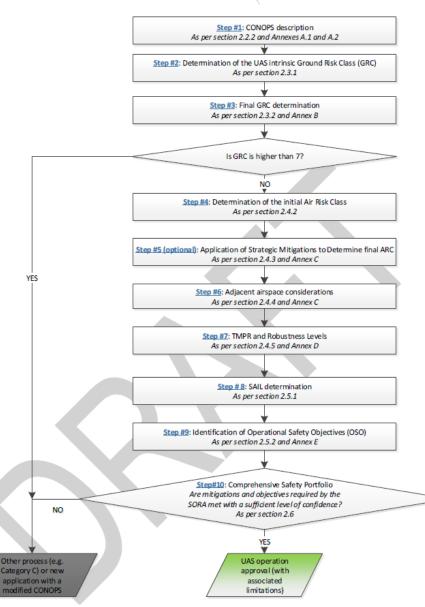
SORA Methodology



WHAT IS SORA?

SORA is a **risk assessment methodology** for drone operations proposed by JARUS, the group of experts that proposes rules for the drone market.

It consists of a series of steps that allow to evaluate the risk of the operation with the drone, designed specifically for the **specific category** defined by EASA.



CONOPS



STANDARD SCENARIO

1- CONOPS Description

- They take place in a flight test center with segregated airspace (with an associated TSA)
- BVLOS conditions
- Over sparsely populated areas
- Outside controlled airspace
- Out of airport environment according to the definition established in ANNEX C V1.3 section 3.11 of the SORA.
- RPAs <3m of maximum characteristic dimension (typical kinetic energy expected <34kJ).



ATLAS TSA

GROUND RISK CLASS



2- Initial GRC (unmitigated ground risk)

Intrinsic UAS Ground Risk Class					
Max UAS characteristics dimension	1 m /	3 m / approx.	8 m / approx.	>8 m /	
Max DAS characteristics difficultiension	approx. 3ft	10ft	25ft	approx. 25ft	
	< 700 J	< 34 KJ	< 1084 KJ	> 1084 KJ	
Typical kinetic energy expected	(approx. 529	(approx.	(approx.	(approx.	
	Ft Lb)	25000 Ft Lb)	800000 Ft Lb)	800000 Ft Lb)	
Operational scenarios					
VLOS over controlled area, located					
inside a sparsely populated	1	2	3	5	
environment					
BVLOS over sparsely populated					
environment (over-flown areas	2	3	4	6	
uniformly inhabited)					
VLOS over controlled area, located	3	4	6	8	
inside a populated environment	3	4		8	
VLOS over populated environment	4	5	7	9	
BVLOS over controlled area, located	5	6	8	10	
inside a populated environment) 3	O	0	10	
BVLOS over populated environment	6	7	9	11	

FINAL GROUND RISK CLASS



3- Final GRC (mitigated ground risk)

		Robustness Level			
Mitigation number	GRC adaptation	Low / None	Medium	High	Correction
M1	An Emergency Response Plan (ERP) is in place, operator validated and effective	1	0	-1	-1
M2	Effects of ground impact are reduced	0	-1	-2	0
М3	Technical containment in place and effective	0	-2	-4	0
Total correction					-1

Final GRC

	GRC
Initial	3
An effective Emergency Response Plan is available	- 1
for use, and has been validated	
Systems are available that reduce the effects of	+0
impact on people or land	
There are technical containment systems	+ 0
implemented and effective	
Final GRC	2

MITIGATIONS FOR GROUND RISK



Emergency response plan: high robustness level

- -High Integrity level:
 - ✓ Proportional to risk and complexity of the operations
 - ✓ Define criteria to identify an emergency situation
 - ✓ Reduces the risk to people on gound (by limiting the "scalating effect"
 - ✓ Easy / effective to use
 - ✓ Clearly defines the roles and responsibilities of crew members
 - √ Remote pilots receive theoretical and practical training related to ERP
- -High Assurance level: the adequacy of contingency and emergency procedures should be proved trough
 - ✓ Dedicated flight tests, or,
 - ✓ simulations, providing its representativeness; and
 - √ the procedures, flight tests and simulations are validated by a competent third party

Reducing Ground impact: low robustness level

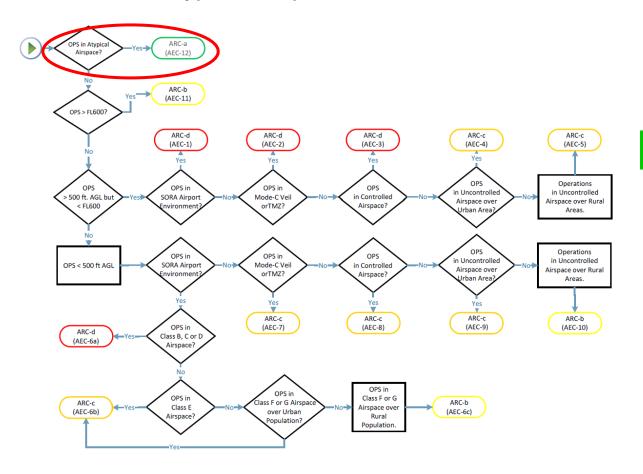
- Considering a small (<3m → MTOW <25kg) RPAS, no parachute is considered

AERIAL RISK CLASS



4- Initial ARC (aerial risk class)

-TSA: segregated airspace → "atypical" airspace according to SORA Definition of Atypical Airspace in SORA Annex C V1.3, section 3.10



ARC-a

Lowest level of ARC since in segregated airspace no other airspace users are expected

AERIAL MITIGATIONS



- 5- Strategic Mitigation: no need for strategic mitigations
- 6- Adjacent Airspace Consideration: F or G airspace

Containment Objectives					
Operational Case	Final ARC is ARC-d	The final ARC is other than ARC-d and the operation is not conducted adjacent to ARC-d airspace	The final ARC is other than ARC-d and the operation is conducted adjacent to ARC-d airspace		
Containment Robustness Level	N/A	Low	High		

- Containment integrity: recommended loss of containment ≤ 1 event per
 100 flight hours (1E-2/FH)
- •Containment assurance: the **operator should declare** that the mitigations in place will contain the UAS in the operation volume

AERIAL MITIGATIONS AND SAIL



7- Tactical Mitigation Performance Requirement (TMPR) and Robustness Levels Strategic Mitigation

Final ARC	Tactical Mitigation Performance Requirements (TMPR)	TMPR Level of Robustness
ARC-d	High	High
ARC-c	Medium	Medium
ARC-b	Low	Low
ARC-a	No requirement	No requirement

8- SAIL determination

Final GRC: 2

Final ARC: a



SAIL Determination					
	Final ARC				
Final	а	b	С	d	
GRC					
1	Ι	II	IV	VI	
2	Ι	II	IV	VI	
3	II	II	IV	VI	

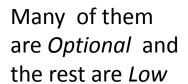
OPERATIONAL SAFETY OBJECTIVES



9- Identification of Operational Safety Objectives (OSOs)

-Lowest SAIL level → less demanding requirements

OSO Number		SAIL					
(in line with Annex E)		I	11	ш	IV	٧	VI
	Technical issue with the UAS						
OSO#01	Ensure the operator is competent and/or proven	0	L	М	н	н	Н
OSO#02	UAS manufactured by competent and/or proven entity	0	0	L	М	Н	Н
OSO#03	UAS maintained by competent and/or proven entity	L	L	М	М	Н	Н
OSO#04	UAS developed to authority recognized design standards	0	0	0	L	М	н
OSO#05	UAS is designed considering system safety and reliability	0	0	L	М	н	Н
OSO#06	C3 link performance is appropriate for the operation	0	L	L	М	н	Н
OSO#07	Inspection of the UAS (product inspection) to ensure consistency to the ConOps	L	L	М	М	Н	Н
OSO#08	Operational procedures are defined, validated and adhered to	L	М	н	Н	Н	Н
OSO#09	Remote crew trained and current and able to control the abnormal situation	L	L	М	М	н	н
OSO#10	Safe recovery from technical issue	L	L	М	М	Н	Н
	Deterioration of external systems supporting						
OSO#11	UAS operation Procedures are in-place to handle the deterioration of external systems supporting UAS operation	L	м	н	н	н	н
OSO#12	The UAS is designed to manage the deterioration of external systems supporting UAS operation	L	L	М	м	Н	Н
OSO#13	External services supporting UAS operations are adequate to the operation	L	L	М	н	Н	н
	Human Error						
OSO#14	Operational procedures are defined, validated and adhered to	L	М	Н	Н	Н	Н
OSO#15	Remote crew trained and current and able to control the abnormal situation	L	L	М	М	Н	Н
OSO#16	Multi crew coordination	L	L	М	М	Н	Н
OSO#17	Remote crew is fit to operate	L	L	М	М	н	Н
OSO#18	Automatic protection of the flight envelope from Human Error	0	0	L	М	н	Н
OSO#19	Safe recovery from Human Error	0	0	L	М	М	Н
OSO#20	A Human Factors evaluation has been performed and the HMI found appropriate for the mission	0	L	L	М	м	н
	Adverse operating conditions		-	\vdash	\vdash	\vdash	\vdash
OSO#21	Operational procedures are defined, validated and adhered to	L	М	н	Н	н	Н
OSO#22	The remote crew is trained to identify critical environmental conditions and to avoid them	L	L	М	М	М	Н
OSO#23	Environmental conditions for safe operations defined, measurable and adhered to	L	L	М	М	Н	Н
OSO#24	UAS designed and qualified for adverse environmental conditions	0	0	М	н	н	н



OSO Number		SAIL
(in line with		I
Annex E)	- 1 · 1 · · · · · · · · · · · · · · · ·	-
	Technical issue with the UAS	
OSO#03	UAS maintained by competent and/or proven entity	L
OSO#07	Inspection of the UAS (product inspection) to ensure	1
	consistency to the ConOps	
OSO#08	Operational procedures are defined, validated and	1
	adhered to	L
OSO#09	Remote crew trained and current and able to control	1
	the abnormal situation	
OSO#10	Safe recovery from technical issue	L
	Deterioration of external systems supporting UAS	
	operation	
OSO#11	Procedures are in-place to handle the deterioration of	1
	external systems supporting UAS operation	
OSO#12	The UAS is designed to manage the deterioration of	1
	external systems supporting UAS operation	
OSO#13	External services supporting UAS operations are	1
	adequate to the operation	
	Human Error	
OSO#14	Operational procedures are defined, validated and	1
	adhered to	
OSO#15	Remote crew trained and current and able to control	
	the abnormal situation	
OSO#16	Multi crew coordination	L
OSO#17	Remote crew is fit to operate	L
	Adverse operating conditions	
OSO#21	Operational procedures are defined, validated and	-
	adhered to	L
OSO#22	The remote crew is trained to identify critical	
	environmental conditions and to avoid them	L
OSO#23		
030#23	Environmental conditions for safe operations defined,	L
	measurable and adhered to	

COMPREHENSIVE SAFETY PORTFOLIO



10- Comprehensive Safety Portfolio

- -Based on level of robustness of previous OSOs, the level of confidence is adequate so the operation can be safely conducted.
- -Additional requirements to those identified by the SORA (security, environmental protection, etc.) as well as relative stakeholders (environmental protection agencies, national security bodies, etc.)

BIG DRONES

In case of bigger drones: RPAs <8m of maximum characteristic dimension

→ associated to MTOW>25kg, the GRC would be 4 without mitigations.

In order to reach the same final GRC as in previous case so the same SAIL Level, it would be required to include a system to reduce the effect of a ground impact of medium robustness → parachute.

APPLICATION



This risk assessment has been used for authorization application of drone flights in ATLAS in the scope of ALADDIN project

ALADDIN project

Study, design, develop, and evaluate, a **counter drone system** as a complete solution to the growing drone threat problem, building upon a state-of-the-art system and enhancing it by researching on various **detection and neutralization technologies** (program H2020)





Horizon 2020 European Union funding for Research & Innovation

First authorization in Spain applying article 43 of current Spanish drone regulation for exemption drone flights (drones flying at night without lights to represent real case scenario)

ATLAS

ATLAS is a flight test center located in Villacarrillo, Jaen, Spain, designed for drone operations.

ATLAS counts with a segregated airspace (**TSA**) of 1,000 km2 (30x35 km), and up to 5000 feet height AMSL.



SUMMARY



- -SORA methodology followed for the risk assessment
- -Analysis of operations in flight test centers in TSA (segregated areas) over sparsely populated areas
- -GRC would depend on the size of the drones
- -ARC has the lowest level since TSA is considered an atypical airspace, where manned aircraft cannot go
- -Drones MTOW>25 kg would need a parachute for the same SAIL level
- -AESA has published these standard scenarios according to this analysis
- -ATLAS is a flight test center with a TSA which will be used for ALADDIN project