



# **ALADDIN PROJECT**

SHERPA

WORKSHOP

12 APRIL 2019





# **AGENDA**

- → Introduction
- → Project description
- → Pilot experiments
- → Next Steps
- → Conclusion

# **ALADDIN**

# Advanced hoListic Adverse Drone Detection Identification & Neutralization

- → H2020 Programme
- → Research and Innovation Action

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# PROJECT ORIGIN

Where does it come from?

### A BIT OF HISTORY – CALL FOR PROPOSAL

- → Secure societies Protecting freedom and security of Europe and its citizens
  - > Fight against Crime and Terrorism

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Detection and neutralization of rogue/suspicious light drone/UAV flying over restricted areas, and involving as beneficiaries, where appropriate, the operators of infrastructure



### PROPOSAL – GRANT AGREEMENT

- → Proposal selected in January 2017
- → Grant Award in August 2017
- → Start in September 2017
- → Duration: 36 months 3 years
- → 2 Cycles / Iterations
  - > Beta version 18 m February 2019
  - Final version 36 m August 2020
- → Security EU Restricted

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- > Nature of the topic: terrorism and organized crime activities
- > Sensitiveness of some matters / deliverables
  - gap analysis, vulnerability assessment, neutralisation tools and development of new capabilities









# PROJECT DESCRIPTION

What is it about?

#### ACTION / PROJECT MAIN OBJECTIVES

- → Study and develop a state-of-the-art, global, and extensible system to
  - Detect, Localise, Classify, and Neutralize :
    - suspicious, and potentially multiple, light UAVs over restricted areas
- → Build a Counter-UAV system
  - Using BOREADES as the foundation
- → Take into account Operational Constraints
  - > Ease of use and deployment,
  - > Quality of detection
  - Safety
- → Provide tools for operational support

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- Investigations
- > Training





#### OTHER OBJECTIVES

#### → Assess

- > Relevant technology
- > Threat trends
- > Regulations
- Societal, Ethical and Legal (SoEL) frameworks
- → Develop new knowledge for
  - > LEAs,
  - > Infrastructure designers, constructors, and operators
- → Develop innovative Curricula

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- > E-learning
- On site training









# CONSORTIUM

Who is involved

#### CONSORTIUM – 18 PARTNERS

- → 3 Industrial leading companies
  - Diginext (DXT), CS, IDS
- → 3 Innovative SMEs
  - > SIRC, MC2, HGH
- → 3 European Technical Research Centres
  - > CERTH, Fraunhofer IDMT, PIAP
- → 1 European Aeronautic Expert Centre
  - FADA CATEC
- → 1 European Research Centre and Academic Institute
  - > VUB
- → 1 World-class Infrastructure company

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- Acciona Construcion
- → 6 LEAs (End Users): KEMEA, CAST/DSTL, MIF, PJ, MIPS, ADM





# CONSORTIUM - EUROPEAN DIMENSION











# **IMPLEMENTATION**

How is it implemented

## SOME FIGURES AND CONSTRAINTS

- → 9 Work Packages
- → 37 Tasks
- 2 Cycles / Iterations
- → 6 Milestones
- →99 Deliverables
  - 12 EU Restricted => 21
  - 66 Confidential => 59
    - -21 to be reviewed by SAB security perspective
  - 19 Public => 19

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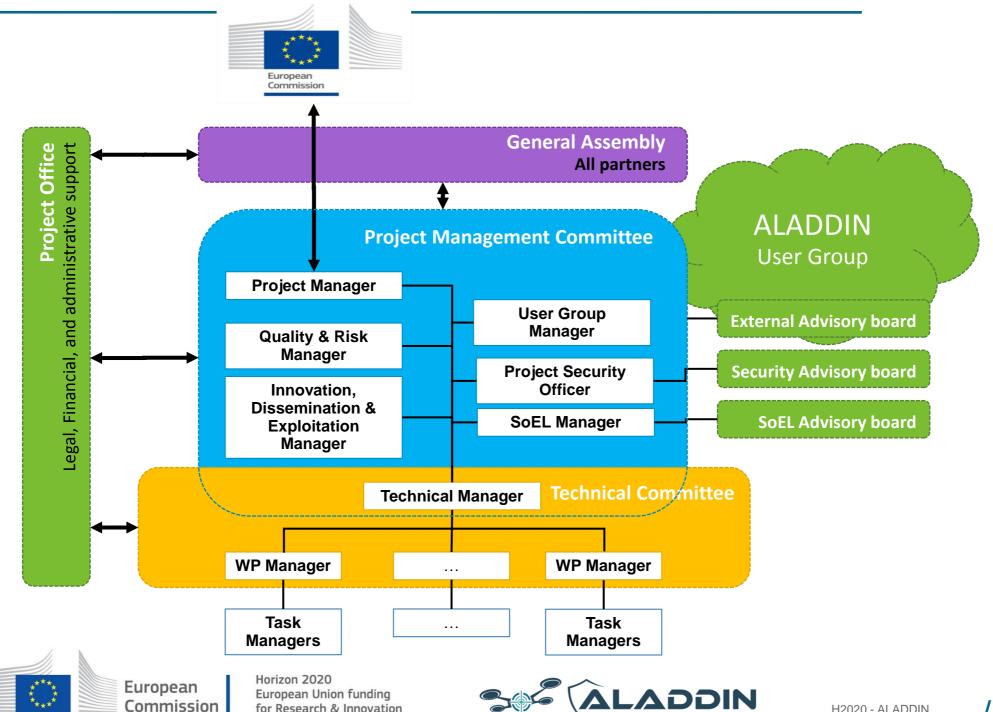
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# MANAGEMENT STRUCTURE

Commission







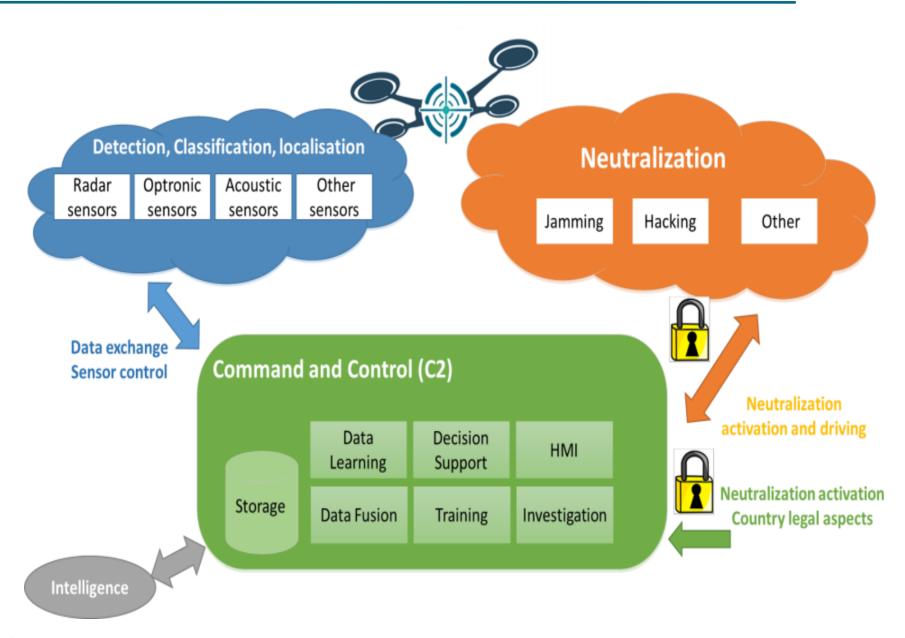
# ARCHITECTURE

What is the system about?

## PLATFORM / SYSTEM CONCEPT

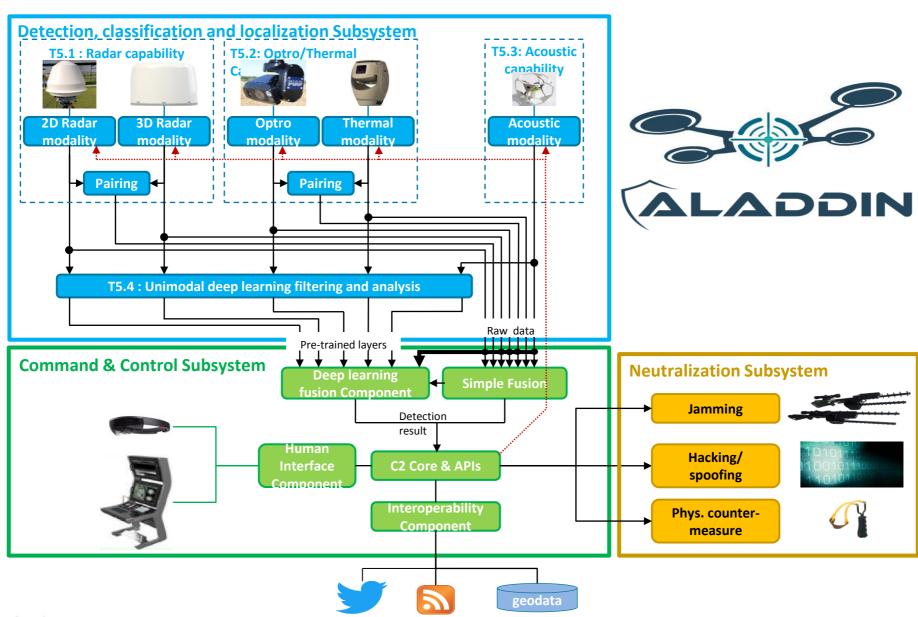
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### NOTIONAL ARCHITECTURE





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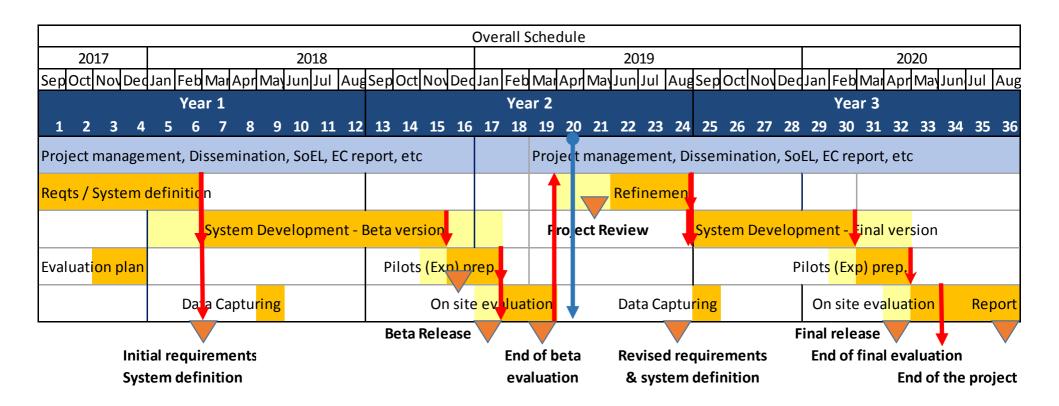


# **PROGRESS**

Where are we?

#### SCHEDULE – PROGRESS

#### → Where we stand





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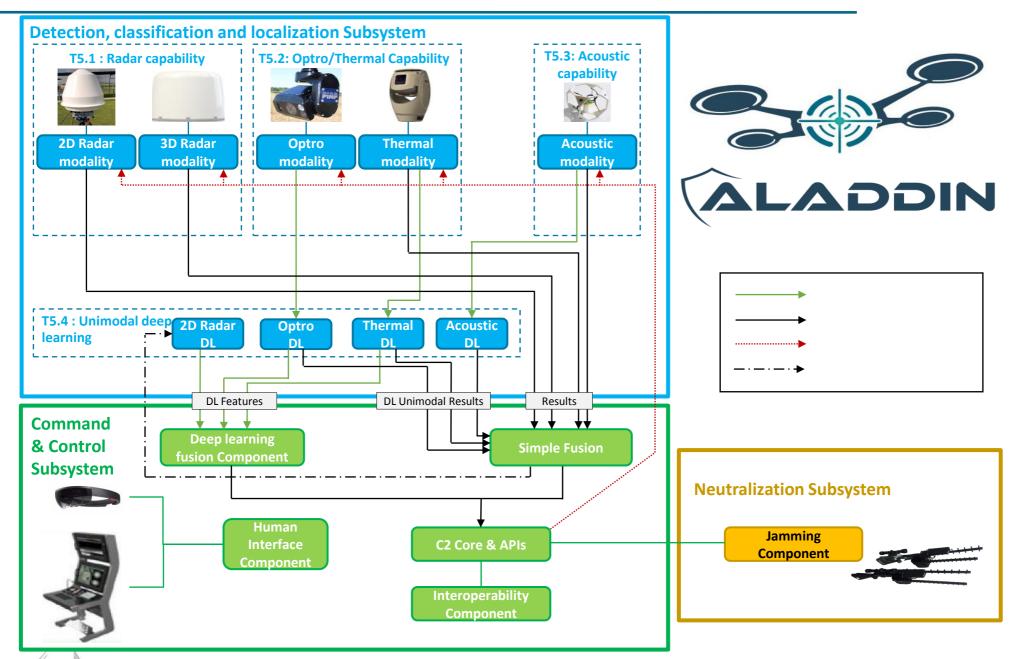




# BETA VERSION

Which system under evaluation?

# **BETA VERSION**





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# PILOT EXPERIMENTS

How to evaluate the system?

# **ATLAS Experimental Test Center**

- Location
  - Flight test center for drones: www.atlascenter.aero
  - TSA: Temporary Segregated Airspace (30x35km up to 5.000ft AMSL)
    - Be able to perform BVLOS flights under current Spanish regulation
  - Hangars for drone and equipment logistics
  - Offices for workshops, meetings, etc.



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# **ATLAS Experimental Test Center**

- Possibility to perform high risk operations with drones due to the activation of the TSA
- Permits for flights at night conditions without lights under exception article of Spanish regulation (article 43)
  - Alignment with future European regulations → definition of a standard scenario based on SORA risk assessment



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# **2019 ALADDIN Demonstration experiments**

Beta version of ALADDIN system

Integration week					
JANUARY 2019					
Monday 21 <sup>st</sup>	Installation & start of tests				
Tuesday 22 <sup>nd</sup>	Integration tests				
Wednesday 23 <sup>rd</sup>	Integration tests				
Thursday 24 <sup>th</sup>	Integration tests				
Friday 25 <sup>th</sup>	Integration tests				

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Experiments & Training week					
FEBRUARY 2019					
Monday 4 <sup>th</sup>	Set up and continuation of				
	integration				
Tuesday 5 <sup>th</sup>	LEA training - Experiments				
Wednesday 6 <sup>th</sup>	LEA training				
	DEMO DAY preparation				
Thursday 7 <sup>th</sup>	ursday 7 <sup>th</sup> DEMO DAY				
Friday 8 <sup>th</sup>	Evaluation of ALADDIN				
	Collecting equipment				



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### **Pilot scenarios**

- Main situations identified in ALADDIN project
  - Potential UAV actions
    - Malicious intentions
    - Negligent UAV
    - Accidental situation
  - Discussed scenarios:
    - Secured facility: prisons, nuclear plants, dams, other critical infrastructures.
    - Airports
    - Governmental buildings
    - Temporary public events: concerts, sports events, agricultural shows, VIP speaking event
  - Environments:
    - Rural
    - Urban









## **Pilot scenarios**

- Evaluation framework
  - Three main threat scenarios considered:
    - A drone invades the protected area.
    - A drone is flying in the protected area at different conditions (heights, distances, etc.)
    - A swarm of drones is flying in the protected area
    - Night flights



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## **Drones**

- Two types of drones used as intruder drones
  - Multicopter: different sizes available

Drone	Quantity	Weight (kg)	Size (cm)	Detection
DJI Phantom 3	6	1,3	35	Yes
DJI Phantom 4	1	1,4	35	Yes
DJI Matrice 600	1	15	170	Yes











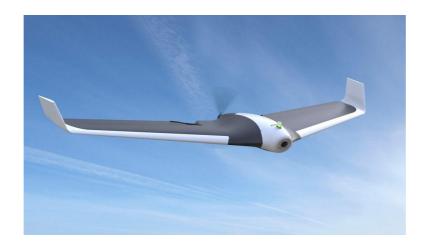
## **Drones**

- Two types of drones used as intruder drones
  - Fixed wing:

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Drone	Quantity	Weight (kg)	Span (cm)	Detection
Parrot Disco	7-8	0,75	115	Yes



# Testing on different weather conditions

- Different weather / light conditions have tested during integration phase
  - Foggy conditions
    - Difficulty for detection with the thermal infrared, and also camera tracking
  - Flight at night
    - Intruder drone without lights to give more representativeness
    - Impossible to detect in very dark conditions as in ATLAS with cameras. No effect on radar – good detections.
- Other circumstances which may affect:
  - Temperature, cloudy / clean sky, backlighting effect due to sun position,
  - Trajectories followed by the intruder drone, velocities, etc.









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# **NEXT STEPS**

What's next?

#### END OF REPORTING PERIOD

- → Preparation & submission (April) of Periodic Report (18 month)
- → Evaluation by European Commission
  - > Review with REA and experts 16 May
- → Start of second iteration (March 2019) => Final version (June 2020)
  - > Workshop June/July
    - Review requirements, ConOps, Use Cases
    - Review architecture and functional specifications
    - Roadmap for Neutralisation means
  - Data capturing session mid-Sept in Greece
  - Development of components, Curriculum
  - Integration, test and evaluation + Training
    - May 2020 in Greece

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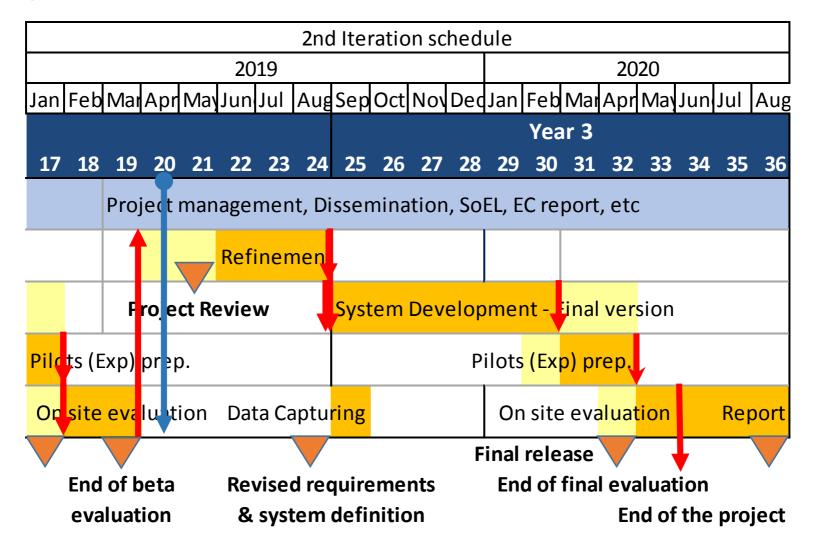
> Final Report - Aug 2020





#### SCHEDULE - PROGRESS

#### → The plan till the end





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# CONCLUSION

#### **ALADDIN - CONCLUSION**

- → European H2020 Project
- → 3 year duration Sept 2017 => Aug 2020
- → Developing a Counter UAV
  - > Building on BOREADES system
  - Sensor suite with acoustic capability and deep learning filtering
  - Innovative neutralisation capability
- → Experiments in real environments
  - > Open field Urban area
- → Enhance Security and provide tools for LEAs & Infrastructure Constructors and Operators
- → Open to external users, experts, advisors

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## **END OF PRESENTATION**

→ Any question?

- → Web site
  - https://aladdin2020.eu/

- → Project coordinator
  - > Patrick.garnier@diginext.fr



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